



**2001 6**

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가

가

가

가

가

가

가

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. . . . . 1

1. . . . . 1

2. . . . . 4

3. 가 . . . . . 4

. . . . . 5

1. . . . . 5

2. . . . . 7

3. . . . . 7

4. . . . . 8

5. **BTE work simulator** . . . . . 8

6. . . . . 11

. . . . . 13

1. . . . . 13

2. . . . . 15

3. . . . . 17

4. . . . . 19

5. . . . . 21

6. . . . . 23

7. . . . . 25

8.	.....	27
9.	.....	29
10.	, , , , 1 , 1	
	.....	31
.	.....	33
1.	.....	33
2.	.....	35
3.	.....	39
.	.....	40
	.....	42
	.....	46

1.	. . . . .	12
2.	. . . . .	13
3.	. . . . .	14
4.	. . . . .	18
5.	. . . . .	20
6.	. . . . .	22
7.	. . . . .	24
8.	. . . . .	26
9.	. . . . .	28
10.	. . . . .	30
11.	. . . . .	32

1.	.....	6
2.	.....	16
3.	.....	16



가  
가

, 2001 3 4  
BTE work simulator

17

1. 6 15.58±  
8.92 Nm , 7 24.20±5.41 Nm, 8 37.43  
±8.79 Nm 가 가 (p<0.001).

2. 6 6.80±4.78  
Nm , 7 15.55±8.04 Nm, 8 28.68±  
9.75 Nm 가 가 (p<0.001).

3. 6 320.07±196.70 Joules ,  
7 845.50±512.27 Joules, 8 898.00±  
292.74 Joules 가 가 (p<0.001).

4. (p<0.05).

5. (p<0.05).

6.

( $p < 0.05$ ).

7.

( $p < 0.001$ ),

가 ( $p < 0.01$ ). 1

( $p < 0.05$ )

가

( $p < 0.01$ ). 1

가 ( $p < 0.01$ ). 1

,

가 ( $p < 0.001$ ).

BTE work simulator

. BTE work simulator

,

가

BTE work simulator

1.

(locomotion)

1996).

(Newsam ,

(Hughes

, 1992),

(Brubaker, 1986).

transfer mat skill

(Somers, 1991).

가

가

가

(Granger , 1993).

(Brauer Hertig,

1981; Brubaker , 1983) force plates isokinetic dynamometer

simulator

3

force transducer

가

가 (Veeger , 1992).

(Rodgers , 1994; Ruggles , 1994).

가

(Veeger , 1991; Veeger , 1992; Robertson , 1996).

(1993 )

5

(1994 )

가

(1999 )

17

가

가

BTE work simulator

가

가 가 (Curtis Engalitcheff, 1981). BTE work simulator

, 가

. (static strength)

BTE work simulator

가

가

가

(simulate)

. 가

가

가

. BTE work simulator

가

BTE work

simulator

.

## 2.

BTE

work simulator

- 1) 가  
가
- 2)
- 3) BTE work simulator
- 4)

## 3. 가

가  
,  
가 .  
, , ,  
가 .  
, , , 1  
가 .

•

**1.**

BTE work simulator

,

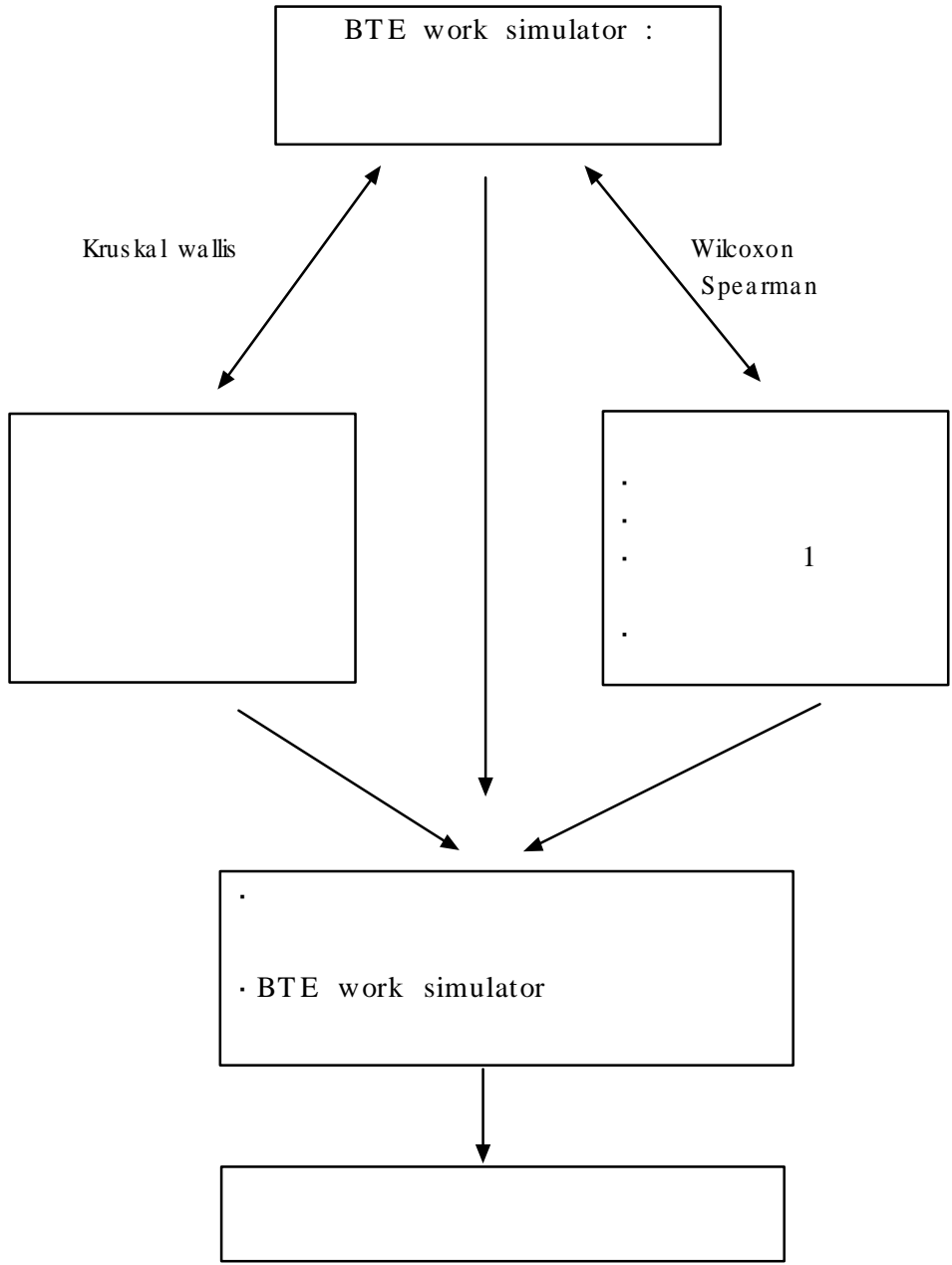
,

,

,

,

.



< 1 >



## 2.

2001 3 12 3 17 , 3 18  
4 30 BTE work  
simulator .

## 3.

1) 가 6 8  
, 2) ASIA impairment A, B , 3)  
, 4) 1  
, 5)  
, 6) 20 40  
.  
(dominant hand) , 가  
, , ,

( , 1998).

4.

, , ,  
, ,  
, ,  
, ,

spirometer (Spiropet; Japan)

## 5. BTE work simulator

1) 가

가 46cm

BTE work simulator (Model NO. WS20, Baltimore Therapeutic Equipment Company, Maryland, U. S. A) 141 large wheel .

(olecranon)

partner 7000 .

(hand rim) BTE work

simulator wheel , 가

(simulate) . BTE work simulator

head , BTE work

simulator large wheel 6cm .

가

,

.

BTE work simulator

가

.

2)

가

가

가

가

120 가

( ,

1999 ).

3)

BTE work simulator 가

3 BTE work simulator

(Bhambhani , 1994 ).

4)

BTE

.  
 . 3  
 - , COV(coefficient of  
 variation)가 15%

5 30 .  
 BTE work simulator Manual static mode  
 Quest static menu maximum strength test ,  
 Quest soft ware program

(force level)  
 1/2 ( ) . 3  
 - COV(coefficient of variation)  
 가 15% . 1/2  
 7-9 10  
 30 . automatic mode  
 Quest program ,  
 Quest program .

5) ( )

가  
가  
(force level) 1/2  
가  
가  
metronome(LUX  
;USA) BTE work simulator  
manual dynamic mode Quest program  
, Quest program .

## 6.

BTE work  
simulator Quest soft ware  
SAS ,  
, Kruskal Wallis , Wilcoxon  
,  
, Wilcoxon  
, Spearman

Wilcoxon

가 < 1>

1

1

Wilcoxon

Wilcoxon

< 1>

		(n=17)	(n=15) <sup>†</sup>	p- value
	C6	14.78 ± 6.78	16.65 ± 11.83	
*	C7	26.85 ± 3.07	22.88 ± 5.99	0.533
	C8	36.28 ± 9.30	43.20	
	C6	7.07 ± 3.72	6.44 ± 6.48	
*	C7	18.16 ± 5.28	14.24 ± 8.27	0.208
	C8	27.16 ± 9.18	36.24	
#	C6	332.50 ± 185.91	266.50 ± 178.79	
	C7	1006.25 ± 584.32	631.25 ± 350.86	0.323
	C8	933.00 ± 120.09	1169.00	

<sup>†</sup> : 1 1 ( : \* Nm, # Joules)

•

1.

32.3  
 60.8 1 6.7 ,  
 1 3.7 . 1  
 8 5 < 2>.  
 6 8 7 4 , 8  
 5 17 . ASIA  
 impairment scale A 10 , B 7 .  
 12 , 3 , 2 < 3>.

< 2>

	±		
( )	32.35 ± 5.98	21.00	43.00
( )	16.12 ± 13.91	4	48
(cc)	2529.41 ± 718.39	1300	3800
( )	60.76 ± 59.09	3	240
	1.10 ± 0.84	0	4
	6.71 ± 5.81	0	14
	3.66 ± 4.83	0	13
	9.90 ± 5.82	0	16

< 3 >

---

---

		(%)
	C6	8(47.06)
	C7	4(23.53)
	C8	5(29.41)
ASIA	A	10(58.82)
impairment	B	7(41.18)
		12(70.59)
		3(17.65)
		2(11.76)
		2(11.76)
		8(47.06)
		7(41.18)
		7(41.18)
		10(58.82)
가		9(52.94)
		8(47.06)
		11(64.71)
		6(35.29)
		13(76.47)
		4(23.53)
		5(29.41)
		12(70.59)
		13(76.47)
		4(23.53)

---

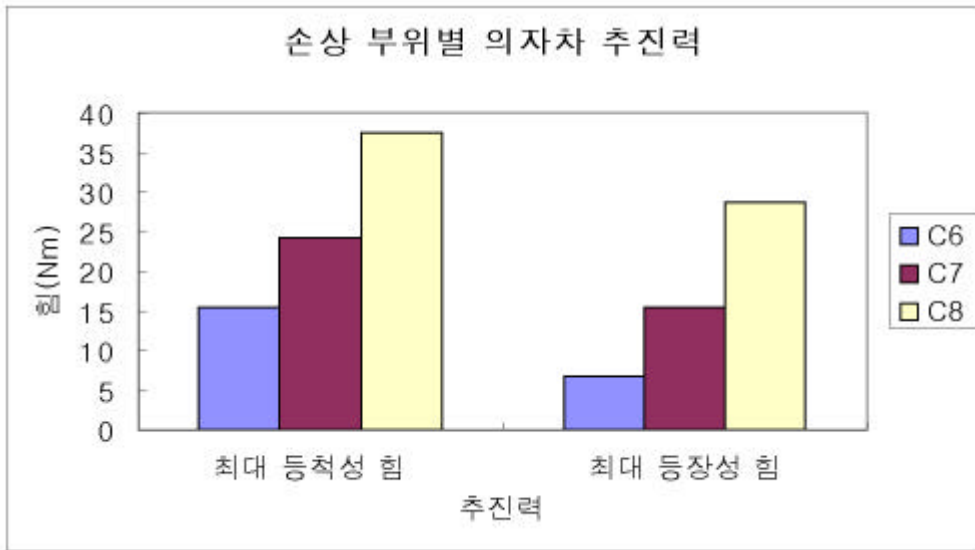


2.

6  $15.58 \pm 8.92$  Nm , 7  
 $24.20 \pm 5.41$  Nm, 8  $37.43 \pm 8.79$  Nm  
( $p < 0.001$ ).

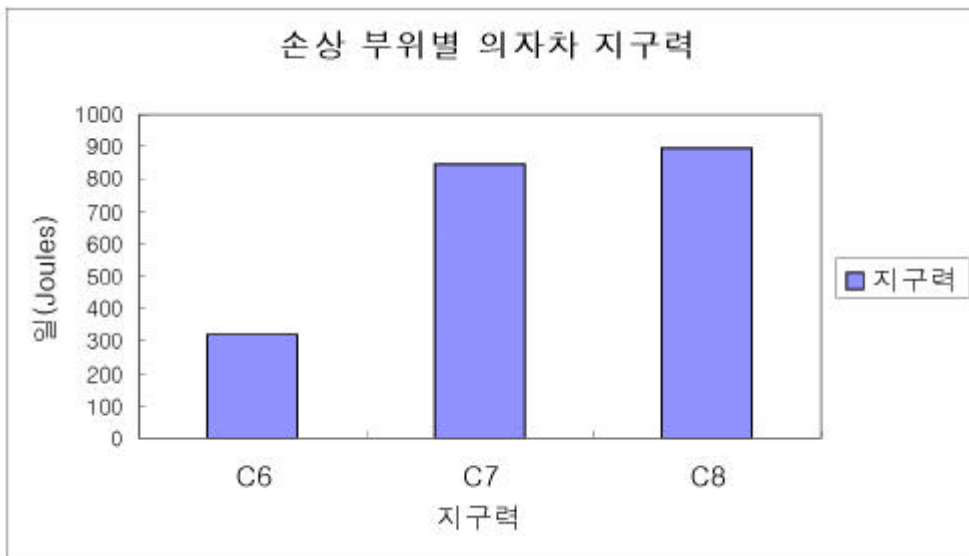
6  $6.80 \pm 4.78$  Nm , 7  
 $15.55 \pm 8.04$  Nm, 8  $28.68 \pm 9.75$  Nm  
( $p < 0.001$ )< 2>.

6  $320.07 \pm 196.70$  Joules ,  
7  $845.50 \pm 512.27$  Joules, 8  $898.00 \pm 292.74$   
Joules ( $p < 0.001$ )< 3>.



< 2>

( : 15.42, p-value 0.0004 : 17.19, p-value 0.0002 )



< 3>

( 14.68 p-value 0.0006 )

**3.**

6 17.30 Nm,  
 7 28.60 Nm, 8 41.05 Nm ,  
 6 14.89 Nm, 7 22.00 Nm,  
 8 30.20 Nm 가  
 (p<0.05).

6 7.21 Nm,  
 7 22.44 Nm, 8 32.62 Nm ,  
 6 6.64 Nm, 7 12.10 Nm, 8  
 20.79 Nm 가  
 (p<0.05).

6 277.00  
 Joules, 7 1003.50 Joules, 8 1083.25 Joules  
 , 6 315.10 Joules, 7  
 632.63 Joules, 8 750.50 Joules  
 가 (p>0.05)< 4>.

< 4 >

		(n=12)	(n=20)
	C6	17.30 ± 12.20	14.89 ± 7.97
*	C7	28.60 ± 2.31	22.00 ± 5.20
	C8	41.05 ± 8.41	30.20 ± 4.10
	†		256.00
p- value			0.0206
	C6	7.21 ± 4.36	6.64 ± 5.15
*	C7	22.44 ± 5.26	12.10 ± 6.99
	C8	32.62 ± 9.70	20.79 ± 2.40
	†		258.00
p- value			0.0206
	C6	277.00 ± 195.80	315.10 ± 178.33
#	C7	1003.50 ± 199.31	632.63 ± 503.56
	C8	1083.25 ± 311.17	750.50 ± 6.36
	†		301.00
p- value			0.0518

† Wilcoxon

( : \* Nm, # Joules)

4.

6  
17.90 Nm, 7 25.23 Nm, 8 38.30 Nm  
, 6 11.40 Nm,  
7 19.05 Nm, 8 33.01 Nm  
가 (p<0.05).

6  
8.19 Nm, 7 16.12 Nm, 8 29.92  
Nm , 6 4.30 Nm,  
7 12.68 Nm, 8 22.48 Nm  
(p>0.05).

6  
341.44 Joules, 7 797.50 Joules, 8  
1017.60 Joules , 6  
237.20 Joules, 7 550.00 Joules, 8  
746.00 Joules  
(p>0.05)< 5>.

< 5 >

		(n=24)	(n=8)
	C6	17.90 ± 10.18	11.40 ± 4.18
*	C7	25.23 ± 5.34	19.05 ± 1.20
	C8	38.30 ± 9.53	33.01
	†		84.00
p- value			0.0387
	C6	8.19 ± 5.27	4.30 ± 2.53
*	C7	16.12 ± 8.57	12.68 ± 5.40
	C8	29.92 ± 10.36	22.48
	†		90.00
p- value			0.0709
	C6	341.44 ± 206.40	237.20 ± 86.10
#	C7	797.50 ± 479.37	550.00 ± 301.23
	C8	1017.60 ± 306.87	746.00
	†		94.00
p- value			0.0644

† wilcoxon

( : \* Nm , # Joules)

5.

		8		6	
	15.20 Nm,	7		24.95 Nm,	8
	33.70 Nm ,			8	
6	15.86 Nm,	7		22.70 Nm,	8
41.17 Nm					
(p>0.05).					
		8		6	
	7.81 Nm,	7		15.87 Nm,	8
	25.63 Nm ,			8	6
	6.04 Nm,	7		12.41 Nm,	8
					31.72
Nm					
(p>0.05).					
		8		6	
	346.17 Joules,	7		801.88 Joules,	
8	987.33 Joules ,			8	
6	272.75 Joules,	7		665.00 Joules,	8
957.33 Joules					
(p>0.05)< 6>.					

< 6 >

		8	(n=15)	8	(n=17)
	C6	15.86 ± 8.11		15.20 ± 10.69	
	C7	22.70 ± 8.02		24.95 ± 4.05	
	C8	41.17 ± 10.30		33.70 ± 6.72	
				240.00	
p- value				0.7915	
	C6	6.04 ± 3.64		7.81 ± 6.21	
	C7	12.41 ± 7.09		15.87 ± 10.03	
	C8	31.72 ± 11.68		25.63 ± 8.57	
				220.00	
p- value				0.3079	
	C6	272.75 ± 135.20		346.17 ± 227.57	
	C7	665.00 ± 533.51		801.88 ± 440.32	
	C8	957.33 ± 223.86		987.33 ± 410.23	
				248.00	
p- value				0.2765	

† Wilcoxon

( : \* Nm, # Joules)



6.

		5		6	
		27.70 Nm,	7	29.13 Nm,	8
	38.30 Nm	,		5	
6	10.73 Nm,		7	22.56 Nm,	8
	33.10 Nm				
	가	( $p < 0.05$ ).			
			5	6	
		12.67 Nm,	7	20.91 Nm,	8
	29.92 Nm	,		5	
6	4.56 Nm,		7	12.65 Nm,	8
	22.48 Nm				
	가	( $p > 0.05$ ).			
			5	6	
		502.25 Joules,	7	984.00 Joules,	8
	1017.60 Joules	,			5
	6	225.00 Joules,		7	680.33
Joules,	8	746.00 Joules			
		가	( $p > 0.05$ )	< 7 >.	

< 7 >

		5	(n=20)	5	(n=12)
	C6		10.73 ± 3.64		27.70 ± 5.55
*	C7		22.56 ± 5.21		29.13 ± 1.89
	C8		33.10		38.30 ± 9.54
	†			67.00	
p-value				0.0402	
	C6		4.46 ± 2.22		12.67 ± 4.47
*	C7		12.65 ± 9.31		20.91 ± 4.49
	C8		22.48		29.92 ± 10.36
	†			78.00	
p-value				0.2241	
	C6		225.00 ± 89.74		502.25 ± 194.32
#	C7		680.33 ± 487.82		984.00 ± 273.67
	C8		746		1017.60 ± 306.87
	†			119.00	
p-value				0.8170	

† Wilcoxon ( : \* Nm, # Joules)

7.

		6		14.89
Nm,	7	23.53 Nm,	8	38.30 Nm ,
		6	17.30 Nm,	7
				26.20
Nm,	8	33.10 Nm		
		가	(p>0.05).	
		6		6.64
Nm,	7	13.71 Nm,	8	29.92 Nm ,
		6	7.21 Nm,	7
17.17 Nm,	8	22.48 Nm		
		가	(p>0.05).	
		6		315.10
Joules,	7	678.68 Joules,	8	1017.60 Joules ,
		6	277.00 Joules,	7
989.00 Joules,	8	746 Joules		
		가	(p>0.05)< 8>.	

< 8 >

		(n=24)	(n=8)
	C6	14.89 ± 7.97	17.3 ± 12.20
*	C7	23.53 ± 5.47	26.20 ± 5.76
	C8	38.3 ± 9.53	33.10 ± 0
	†	137.00	
p- value		0.8447	
	C6	6.64 ± 5.15	7.21 ± 4.36
*	C7	13.71 ± 10.30	17.71 ± 1.05
	C8	29.92 ± 10.36	22.48 ± 0
	†	132.00	
p- value		1.0000	
	C6	315.10 ± 178.33	277.00 ± 195.80
#	C7	678.68 ± 487.52	989.00 ± 267.27
	C8	1017.60 ± 306.87	746.00
	†	136.00	
p- value		0.8869	

† Wilcoxon ( : \* Nm, # Joules)

**8.**

		6		27.70
Nm,	7	28.15 Nm,	8	38.48 Nm ,
		6	10.73 Nm,	7
				22.23
Nm,	8	35.35 Nm		
	가	( $p < 0.05$ ).		
		6		12.67
Nm,	7	10.76 Nm,	8	26.9 Nm ,
		6	4.46 Nm,	7
				16.69 Nm,
	8	29.57 Nm		
	가	( $p > 0.05$ ).		
		6		
502.25 Joules,	7	678.00 Joules,	8	1220.50
Joules ,		6	225.00 Joules,	7
		795.38 Joules,	8	848.25 Joules
			가	( $p > 0.05$ ) < 9 > .

< 9 >

		(n=22)	(n=10)
	C6	10.73 ± 3.64	27.70 ± 5.55
*	C7	22.23 ± 5.53	28.15 ± 2.14
	C8	35.35 ± 7.57	38.48 ± 10.26
	†		230.00
p- value			0.0087
	C6	4.46 ± 2.22	12.67 ± 4.47
*	C7	16.69 ± 8.93	10.76 ± 8.86
	C8	29.57 ± 10.38	26.90 ± 11.93
	†		191.0
p- value			0.2999
	C6	225.00 ± 89.74	502.25 ± 194.32
#	C7	795.38 ± 453.06	678.00 ± 513.32
	C8	848.25 ± 214.26	1220.50 ± 340.12
	†		264.00
p- value			0.0536

† Wilcoxon ( : \* Nm, # Joules)

9.

6  
18.23 Nm, 7 24.60 Nm, 8 41.05 Nm ,  
6 10.80 Nm, 7  
23.64 Nm, 8 30.20 Nm  
가 (p>0.05).  
6 8.49  
Nm 7 10.96 Nm, 8 32.62 Nm ,  
6 3.76 Nm, 7  
19.97 Nm, 8 20.79 Nm  
가 (p>0.05).  
6 359.11  
Joules, 7 805.00 Joules, 8 1083.25 Joules ,  
6 205.40 Joules, 7  
688.00 Joules, 8 750.50 Joules  
가 (p>0.05)< 10>.

< 10 >

		(n=20)	(n=12)
	C6	18.23 ± 10.09	10.80 ± 3.25
*	C7	24.60 ± 4.86	23.64 ± 6.65
	C8	41.05 ± 8.41	30.20 ± 4.10
	†	166.00	
p- value		0.2201	
	C6	8.49 ± 5.18	3.76 ± 1.57
*	C7	10.96 ± 6.43	19.97 ± 10.03
	C8	32.62 ± 9.70	20.79 ± 2.40
	†	189.00	
p- value		0.7407	
	C6	359.11 ± 201.25	205.40 ± 36.81
#	C7	805.00 ± 544.64	688.00 ± 332.14
	C8	1083.25 ± 311.18	750.50 ± 6.36
	†	180.00	
p- value		0.2871	
† wilcoxon		( : * Nm , # Joules)	



10. , , , , 1  
 , 1

가 (p<0.05)  
가  
(p<0.05). (p<0.001),  
가 (p<0.01). 1  
(p<0.05) 가  
(p<0.01). 1  
가 (p<0.01). 1  
,  
가 (p<0.001)< 11>.

< 11>

Spearman		: r
- 0.1981	- 0.3509*	- 0.2777
0.3213	0.3933*	0.3423*
0.6241***	0.4789**	0.4403**
0.1370	0.1567	- 0.0830
- 0.0043	- 0.0117	- 0.1358
0.3136	0.3636*	0.4357**
0.6081**	0.3593	0.1030
0.6367***	0.5895***	0.6078***

\* p<0.05    \*\* p<0.01    \*\*\* p<0.001

•

1.

(performance) 가 ,

(Joynt, 1988). 가

가 . lathes drill press

(Powell , 1991). Curtis Engalitcheff

1979 Baltimore Union Memorial Hospital BTE work simulator .

BTE work simulator simulation

가

가

가

. BTE work simulator

19 가 가

.

가

,

가 (Curtis Engalitcheff, 1997).

BTE work simulator

(simulate)

가 가 (Kennedy Bhambhani, 1991).

BTE work simulator

(dynamic)

(isometric contraction)

가 (Berlin Vermette, 1985). (dynamic power)

가

BTE work simulator

가 , BTE work simulator  
가 가  
가 .  
ASIA impairment A B  
.  
biomechanics가 , 가 가 VO<sub>2</sub>, ventilation,  
가 (Hughes , 1992), 가 120  
(Van der Woude , 1989; ,  
1994)  
가 120 가 .  
가  
(rolling  
resistance) (Brubaker,  
1986), 가  
(Boninger , 2000). 가  
(olecranon)

## 2.

(Nawoczinski, 1987)

Ruggles (1994) 25 32 Cybex  
Isokinetic Machine 가  
(peak torque)  
46, 60, 59 foot pounds 59,  
84, 84 Joules Cybex Isokinetic Machine

Robertson (1996)  
stationary  
wheelchair dynamometer 4  
4 가  
(radial force) 34 N 39 N 가  
(tangential force) 66 N 95 N

Boninger (1997)

SMART wheel

3

(tangential force) 1.3 m/s 45.9 N, 2.2 m/s  
62.1 N . Dallmeijer (1998)

moderate intensity (30-50%  $PO_{max}$ )  
28.1 N, 46.8 N high intensity (60-80%  $PO_{max}$ )

37.0 N,

69.8 N

가

가

가

가

가

. Engel Hildebrant(1973)

가 14- 16%

9- 15%

. Zwiren

Bar-or(1975)

가

가 ( , 1997)

BTE work simulator

BTE

work simulator

가

BTE work simulator



### 3.

,  
BTE work simulator 가  
가 (selection bias)가  
(Berlin Vermette, 1985)  
가  
BTE work simulator 가  
가  
, 가  
가  
BTE work simulator  
가 .

•

2001 3 12

4 30

BTE work simulator 17

1) , 가 가 (p<0.001)

2) (p<0.05).

3) (p<0.05).

4) (p<0.05).

5) (p<0.001), 가 (p<0.01). 1

( $p < 0.05$ )

가 ( $p < 0.01$ ). 1

가 ( $p < 0.01$ ). 1

,

가 ( $p < 0.001$ ).

BTE work

simulator

가

.



9. Boninger ML, Cooper RA, Robertson RN, et al. Three dimensional pushrim during two speeds of wheelchair propulsion. *Am J Phys Med Rehabil* 1997; 76(5): 420-426
10. Boninger ML, Baldwin M, Cooper RA, et al. Manual wheelchair pushrim biomechanics and axle position. *Arch Phys Med Rehabil* 2000; 81: 608-613
11. Brauer RL, Hertig B. Torque generation on wheelchair handrims. Proceedings 1981 biomechanics symposium, ASME/ASCE Mechanics Conference, Colorado. New York: American Society of Mechanical Engineers, 1981, pp 113-116
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## **ABSTRACT**

### **The Force and Endurance during Wheelchair Propulsion in Persons with Cervical Cord Injuries**

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This study was carried out to help the comprehensive rehabilitation of cervical cord injuries by measuring propulsion force and endurance on their wheelchair hand-rims, predicting the differences between neurological levels and analysing the factors which contributed to maintain the wheelchair propulsion force.

The BTE work simulator was used on 17 cervical cord injuries to test the force and endurance during wheelchair propulsion in the occupational therapy room of the National Rehabilitation Center and the Ajou University Hospital.



The results were as follows:

In general wheelchair propulsion force and endurance showed significant differences between neurological levels and types of the life style. And the lower the level were the strength and endurance were higher.

- 1) The mean maximum isometric strengths of C6, C7, C8 were  $15.58 \pm 8.92$  Nm,  $24.20 \pm 5.41$  Nm,  $28.68 \pm 9.75$  Nm ( $p < 0.001$ ).
- 2) The mean maximum isotonic strengths of C6, C7, C8 were  $6.80 \pm 4.78$  Nm,  $15.55 \pm 8.04$  Nm,  $28.68 \pm 9.75$  Nm ( $p < 0.001$ ).
- 3) The mean endurance of C6, C7, C8 were  $320.07 \pm 196.70$  Joules,  $845.50 \pm 512.27$  Joules,  $898.00 \pm 292.74$  Joules ( $p < 0.001$ ).
- 4) The wheelchair propulsion force of cervical cord injuries showed statistically significant differences between those with and without jobs ( $p < 0.05$ ).
- 5) The outdoor wheelchair users showed significantly high maximum isometric strengths compared to the indoor users ( $p < 0.05$ ).
- 6) The maximum isometric strengths were significant high among the wheelchair propulsion exercise group compared to the ROM exercise only group ( $p < 0.05$ ).
- 7) The vital capacity significantly correlated to the maximum isometric strength ( $p < 0.001$ ), the maximum isotonic strength

and the endurance ( $p < 0.01$ ). The daily indoor wheelchair usage highly correlated with the maximum isotonic strength ( $p < 0.05$ ) and the endurance ( $p < 0.01$ ). The daily outdoor wheelchair usage also showed a strong correlation with the maximum isometric strength ( $p < 0.01$ ). The daily indoor/outdoor wheelchair usage is significantly correlated to the maximum isometric strength, the maximum isotonic strength and the endurance ( $p < 0.001$ ).

The BTE work simulator can be used to improve the wheelchair propulsion ability and skills of cervical cord injuries during rehabilitation period. Also it can accelerate the rehabilitation process through wheelchair propulsion exercises in an early stage. In addition the wheelchair propulsion exercise using the BTE work simulator is advantageous to cervical cord injuries integrating into the community with less difficulties. The wheelchair propulsion exercise is one of the most important rehabilitation procedures for the cervical cord injuries to improve their indoor and outdoor community activities. The wheelchair propulsion exercise using the BTE work simulator can improve the quality of life of cervical cord injuries.